

# VARIATEUR DE FREQUENCE J1000



# J1000

Le variateur simple



## Simplicité...

- Installation
- Fonctionnement
- Performances
- Communications
- Qualité

## Objectif simplicité

Le nouveau variateur J1000 a été conçu comme un variateur simple à utiliser dans des applications telles que courroies de transport, ventilateurs et pompes à des puissances nominales faibles.

Bien que son installation, sa configuration et son fonctionnement soient simples, il répond à tous les besoins liés à ces applications.

## Qualité supérieure préservée

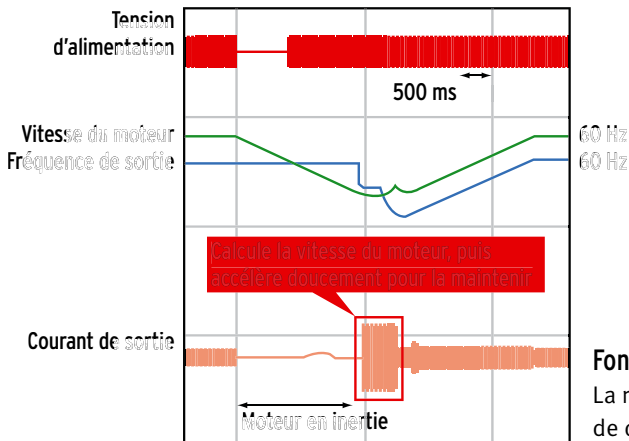
L'obsession de la qualité d'Omron Yaskawa a donné naissance aux produits les plus fiables de l'industrie actuelle. Et nous ne cessons de travailler à améliorer encore la qualité, principe qui s'applique également au nouveau variateur J1000.



# L'essentiel de la variation de fréquence

## Installation

Gain de place grâce au montage côte à côte.



## Fonctionnement

La méthode de calcul de vitesse détecte la vitesse du moteur en cas de coupure de l'alimentation et rétablit la vitesse appropriée.

## Communications

Le variateur J1000 est compatible Modbus grâce à un port dédié sur une carte d'option RS-232 et RS-485. Ce port peut être utilisé pour les opérations de copier/coller du programme du variateur en cas d'utilisation de l'accessoire USB.



## Per ormances

R glez le J1000 sur Exploitation normale pour les applications avec une exigence de surc arge de 120 % et utilisez un variateur de la taille inf rieur e pour effectuer la m me t che.



# VARIATEUR DE FREQUENCE J1000



## J1000 (JZA\_)

### The basic inverter

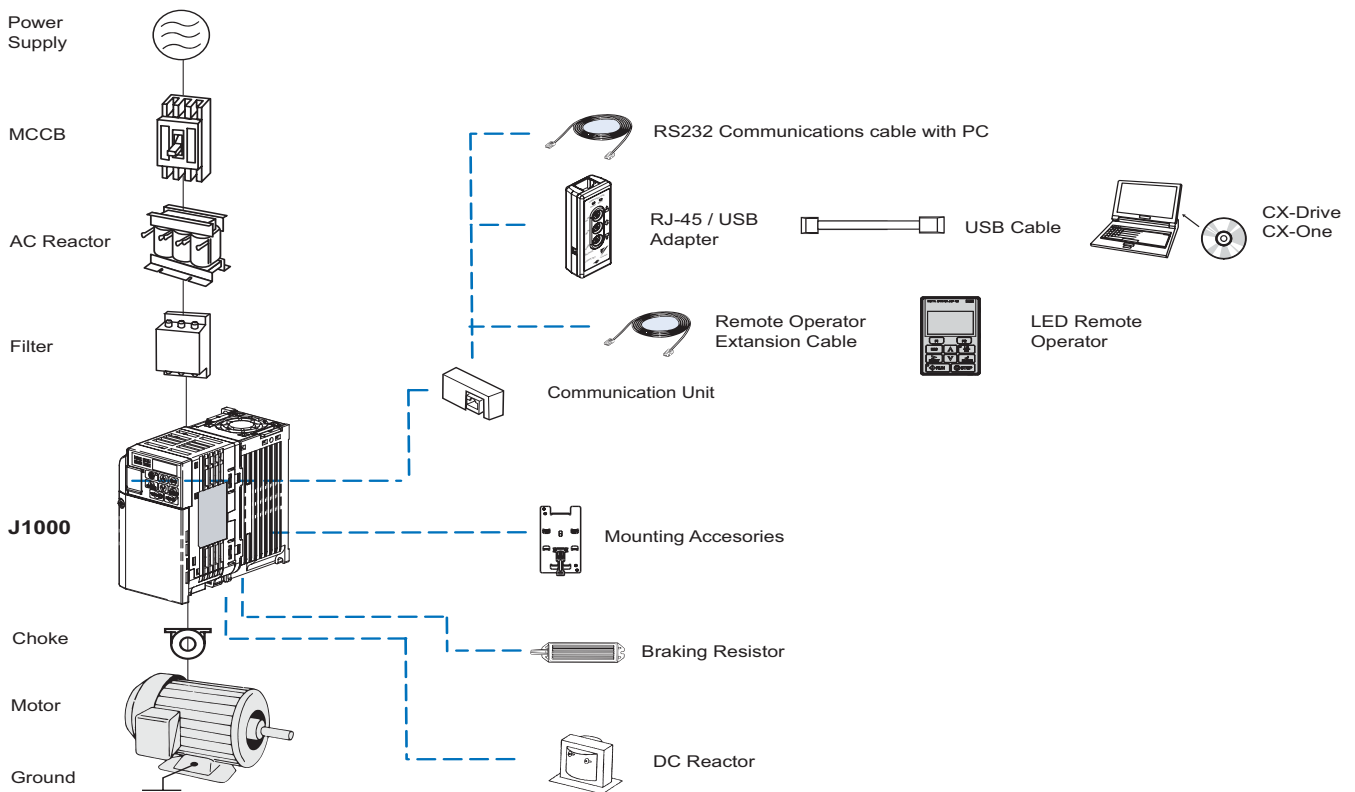
- V/f controlled inverter
- Good torque performance (150% / 3 Hz)
- Double rating ND 120%/1min and HD 150%/1 min
- Overload detection function (150% during 60s)
- Motor thermal function
- Freely configurable V/f curve
- 5 programmable digital input
- 1 programmable digital output
- 1 programmable analog output
- Optional RS-232C/485 communication - Modbus,
- CE, UL, cUL and TUV, RoHS

### Ratings

- 200 V Class single-phase 0.1 to 1.5 kW
- 200 V Class three-phase 0.1 to 4.0 kW
- 400 V Class three-phase 0.2 to 4.0 kW

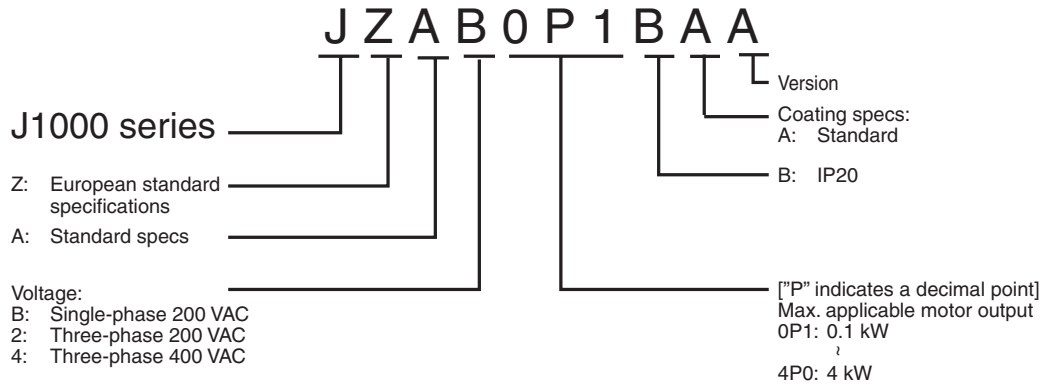


### System configuration



# Specifications

## Type designation



## 200 V class

Single-phase: JZA□		B0P1	B0P2	B0P4	B0P7	B1P5	-	-
Three-phase: JZA□		20P1	20P2	20P4	20P7	21P5	22P2	24P0
Motor kW <sup>1</sup>	For HD setting	0.12	0.25	0.4	1.1	1.5	2.2	4.0
	For ND setting	0.18	0.37	0.55	1.1	2.2	3.0	5.5 <sup>1</sup>
Output characteristics	Inverter capacity kVA	0.3	0.6	1.1	1.9	3.0	4.2	6.7
	Rated output current (A) at HD	0.8	1.6	3.0	5.0	8.0	11.0	17.5
	Rated output current (A) at ND	1.2	1.9	3.5	6.0	9.6	12.0	21.0
	Max. output voltage	Proportional to input voltage: 0..240 V						
	Max. output frequency	400 Hz						
Power supply	Rated input voltage and frequency	Single-phase 200..240 V 50/60 Hz 3-phase 200..240 V 50/60 Hz						
	Allowable voltage fluctuation	-15%..+10%						
	Allowable frequency fluctuation	+5%						

1. Based on a standard 4-pole motor for maximum applicable motor output:  
Heavy Duty (HD) mode with a 150% overload capacity  
Normal Duty (ND) mode with a 120% overload capacity

## 400 V class

Three-phase: JZA□		40P2	40P4	40P7	41P5	42P2	43P0	44P0
Motor kW <sup>1</sup>	For HD setting	0.37	0.55	1.10	1.5	2.2	3.0	4.0
	For ND setting	0.37	0.75	1.5	2.2	3.0	4.0	5.5
Output characteristics	Inverter capacity kVA	0.9	1.4	2.6	3.7	4.2	5.5	7.2
	Rated output current (A) at HD	1.2	1.8	3.4	4.8	5.5	7.2	9.2
	Rated output current (A) at ND	1.2	2.1	4.1	5.4	6.9	8.8	11.1
	Max. output voltage	0..480V (proportional to input voltage)						
	Max. output frequency	400 Hz						
Power supply	Rated input voltage and frequency	3-phase 380..480 VAC, 50/60 Hz						
	Allowable voltage fluctuation	-15%..+10%						
	Allowable frequency fluctuation	+5%						

1. Based on a standard 4-pole motor for maximum applicable motor output:  
Heavy Duty (HD) mode with a 150% overload capacity  
Normal Duty (ND) mode with a 120% overload capacity

## Specifications

### Common specifications

Model number JZA□	Specifications	
<b>Control functions</b>	<b>Control methods</b>	V/f control
	<b>Output frequency range</b>	0.1..400 Hz
	<b>Frequency tolerance</b>	Digital set value: ±0.01% (-10..+50 °C)
		Analogue set value: ±0.1% (25 ±10 °C)
	<b>Resolution of frequency set value</b>	Digital set value: 0.01 Hz (<100 Hz), 0.1 Hz (>100 Hz)
		Analogue set value: 1/1000 of maximum frequency
	<b>Resolution of output frequency</b>	0.01 Hz
	<b>Overload capability</b>	Heavy duty use: 150% rated output current for one minute Normal duty use: 120% rated output current for one minute
	<b>Frequency set value</b>	0..10 V (20 kΩ), 4..20 mA (250 Ω), 0..20 mA (250 Ω) Pulse train input, frequency setting value (selectable)
	<b>Braking torque (short term peak torque)</b>	Short-term average deceleration torque: 150% (up 1.5 kW), 100% (for 1.5 kW), 50% (for 2.2 kW), 20% (for bigger size) Continuous regenerative torque: Approx 20% (125% with optional braking resistor, 10%ED, 10 s, braking transistor built in)
<b>V/f Characteristics</b>	Possible to program any V/f pattern	
<b>Functionality</b>	<b>Inputs signals</b>	Five of the following input signals are selectable: Forward/reverse run (3-wire sequence), fault reset, external fault (NO/NC contact input), multi-step speed operation, Jog command, accel/decel time select, external baseblock, speed search command, UP/DOWN command, accel/decel hold command, LOCAL/REMOTE selection, emergency stop fault, emergency stop alarm, self test
	<b>Output signals</b>	Following output signals are selectable (NO/NC contact output, MA, MB and MC relay: Fault, running, zero speed, speed agree, frequency detection (output frequency <= or => set value), undervoltage detection, minor error, during baseblock, operation mode, inverter run ready, during fault retry, reverse running, during speed search.
	<b>Standard functions</b>	Full-range automatic torque boost, slip compensation, 9-step speed operation (max.), restart after momentary power loss, DC injection braking current at stop/start (50% of inverter rated current, 0.5 sec, or less), frequency reference bias/gain, ME-MOBUS communications (Option), fault retry, speed search, frequency upper/lower limit setting, overtorque detection, frequency jump, accel/decel time switch, accel/decel prohibited, S-curve accel/decel
	<b>Analogue inputs</b>	1 analogue input, 0..10 V, 4..20 mA, 0..20 mA
	<b>Braking/acceleration times</b>	0.01..6000 s
	<b>Display</b>	Optionally frequency, current or set value Error and status LED
<b>Protection functions</b>	<b>Motor overload protection</b>	Electronic thermal overload relay
	<b>Instantaneous overcurrent</b>	Motor coasts to a stop at approx. 250% of inverter rated current
	<b>Overload</b>	Heavy Duty: Motor coasts to a stop after 1 minute at 150% of inverter rated output current Normal Duty: Motor coasts to a stop after 1 minute at 120% of inverter rated output current
	<b>Overvoltage</b>	Motor coasts to a stop if DC bus voltage exceed 410 V (double for 400 V class)
	<b>Undervoltage</b>	Stops when DC bus voltage is approx. 190 V or less (double for 400 V class) (approx. 150 V or less for single-phase series)
	<b>Momentary power loss</b>	Following items are selectable: not provided (stop if power loss is 15 ms or longer), continuous operation if power loss is approx. 0.5 s or shorter, continuous operation
	<b>Cooling fin overheat</b>	Protected by thermister
	<b>Stall prevention level</b>	Stall prevention during acceleration/deceleration and constant speed operation
	<b>Ground fault</b>	Protected by electronic circuit (operation level is approx. 250% of rated output current)
	<b>Power charge indication</b>	Indicates until the main circuit voltage reaches 50 V.
<b>Ambient conditions</b>	<b>Degree of protection</b>	IP20, NEMA1
	<b>Cooling</b>	Cooling fan is provided for 200 V (3-phase) 0.75 kW (1HP) to 4.0 kW, 200V (single-phase) 1.5 kW 400 V 1.5 kW (2HP) to 4.0 kW, others are self-cooling
	<b>Ambient humidity</b>	95% RH or less (without condensation)
	<b>Storage temperature</b>	-20 °C..+60 °C (short-term temperature during transportation)
	<b>Installation</b>	Indoor (no corrosive gas, dust, etc.)
	<b>Installation height</b>	Max. 1000 m
<b>Vibration</b>	Up to 9.8 m/s <sup>2</sup> at 10 to less than 20 Hz, Up to 6.37 m/s <sup>2</sup> at 20 to 50 Hz	

## Dimensions

### IP 20 type 0.1 to 4 kW

Figure 1

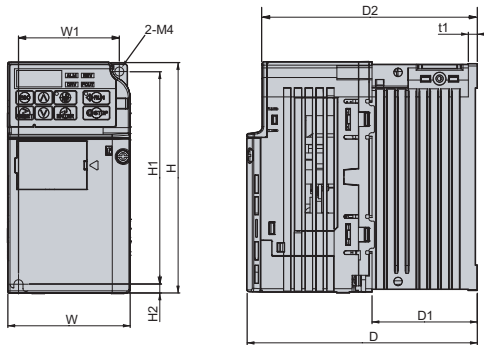
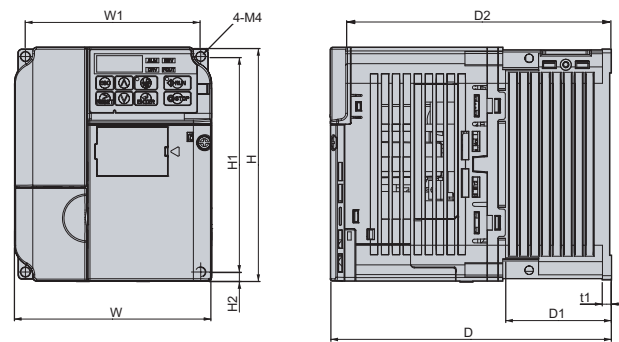
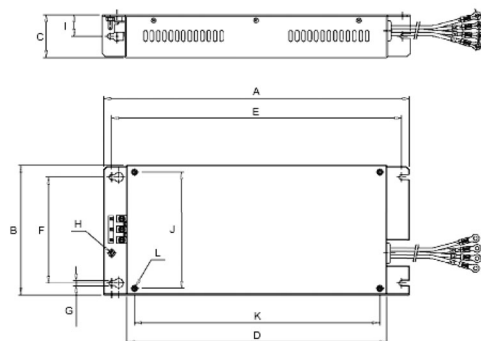


Figure 2



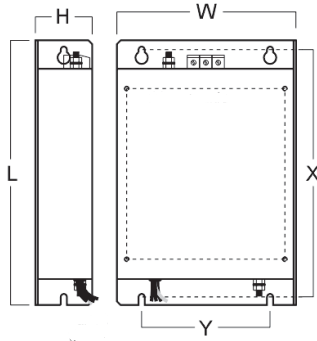
Voltage class	Max. applicable motor output kW	Inverter model JZA□	Figure	Dimensions in mm									
				W1	H1	W	H	D	t1	H2	D1	D2	Weight
Single-phase 200 V	0.12	B0P1	1	56	118	68	128	76	3	5	6.5	67.5	0.6
	0.25	B0P2											0.6
	0.55	B0P4	2	96		108	128	118	5	38.5	109.5	1.0	
	1.1	B0P7						137.5				1.7	
	1.5	B1P5				154	1.8						
Three-phase 200 V	0.12	20P1	1	56	118	68	128	76	3	5	6.5	67.5	0.6
	0.25	20P2											0.6
	0.55	20P4	2	96		108	128	108	5	38.5	99.5	0.9	
	1.1	20P7						128				1.1	
	1.5	21P5				129	1.7						
	2.2	22P2	137.5	140	143	5	58	120.5	1.7				
	4.0	24P0							129	1.7			
Three-phase 400 V	0.37	40P2	2	96	118	108	128	81	5	5	10	72.5	1.0
	0.55	40P4											99
	1.1	40P7	2	128		137.5	143	58	129	1.7			
	1.5	41P5								145.5	1.7		
	2.2	42P2				154	1.7						
	3.0	43P0	143	143	65	134.5	28	90.5	1.7				
	4.0	44P0							143	2.4			

### Schaffner footprint Filters



Schaffner model		Dimensions												Weight KG
		A	B	C	D	E	F	G	H	I	J	K	L	
3x200 V	A1000-FIV2010-SE	194	82	50	160	181	62	5.3	M5	25	56	118	M4	0.40
	A1000-FIV2020-SE	169	111	50	135	156	91	5.5	M5	25	96	118	M4	0.58
	A1000-FIV2030-SE	174	144	50	135	161	120	5.3	M5	25	128	118	M4	0.90
1x200 V	A1000-FIV1010-SE	169	71	45	135	156	51	5.3	M5	22	56	118	M4	0.44
	A1000-FIV3005-SE	169	111	50	135	156	91	5.3	M5	25	96	118	M4	0.75
3x400 V	A1000-FIV3010-SE	169	111	45	135	156	91	5.3	M5	22	96	118	M4	0.5
	A1000-FIV3010-SE	169	111	45	135	156	91	5.3	M5	22	96	118	M4	0.7
	A1000-FIV3020-SE	174	144	50	135	161	120	5	M5	25	128	118	M4	0.9

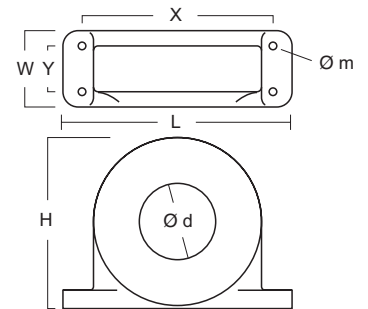
### Rasmi footprint Filters



Rasmi model		Dimensions						Weight KG
		W	H	L	X	Y	M	
3x200 V	A1000-FIV2010-RE	82	50	194	181	62	M4	0.8
	A1000-FIV2020-RE	111	50	194	181	62	M4	1.1
	A1000-FIV2030-RE	144	50	174	161	120	M4	1.3
1x200 V	A1000-FIV1010-RE	71	45	169	156	51	M4	0.6
	A1000-FIV1020-RE	111	50	169	156	91	M4	1.0
3x400 V	A1000-FIV3005-RE	111	45	169	156	91	M4	1.1
	A1000-FIV3010-RE	111	45	169	156	91	M4	1.1
	A1000-FIV3020-RE	144	50	174	161	120	M4	1.3

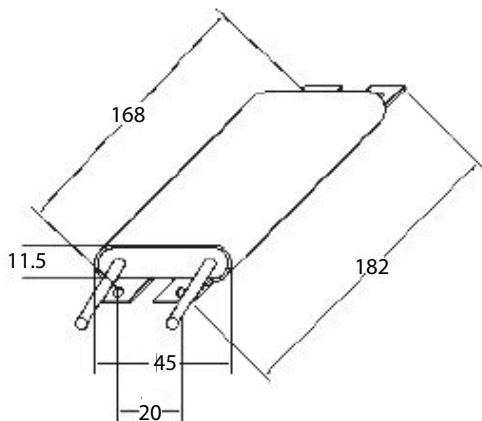
### Chokes

Description	D diameter	Motor KW	Dimensions						Weight Kg
			L	W	H	X	Y	m	
A1000-FEV2102-RE	21	< 2.2	85	22	46	70	-	5	0.1
A1000-FEV2515-RE	25	< 15	105	25	62	90	-	5	0.2

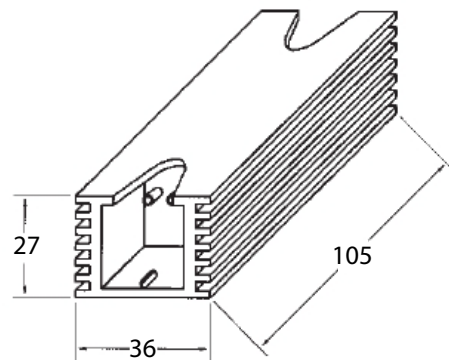


### Resistor Dimensions

A1000-REJ0K15xxx

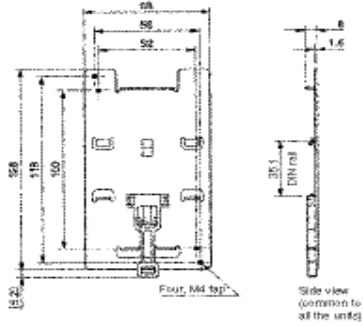


A1000-REJ0K10xxx

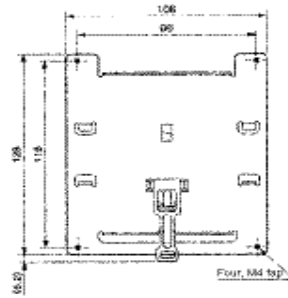


## DIN rail mounting bracket

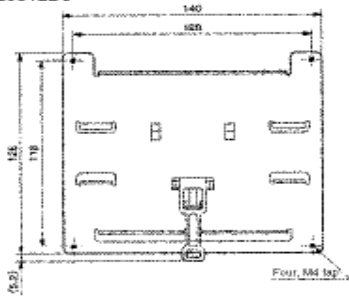
EZZ08122A



EZZ08122B



EZZ08122C

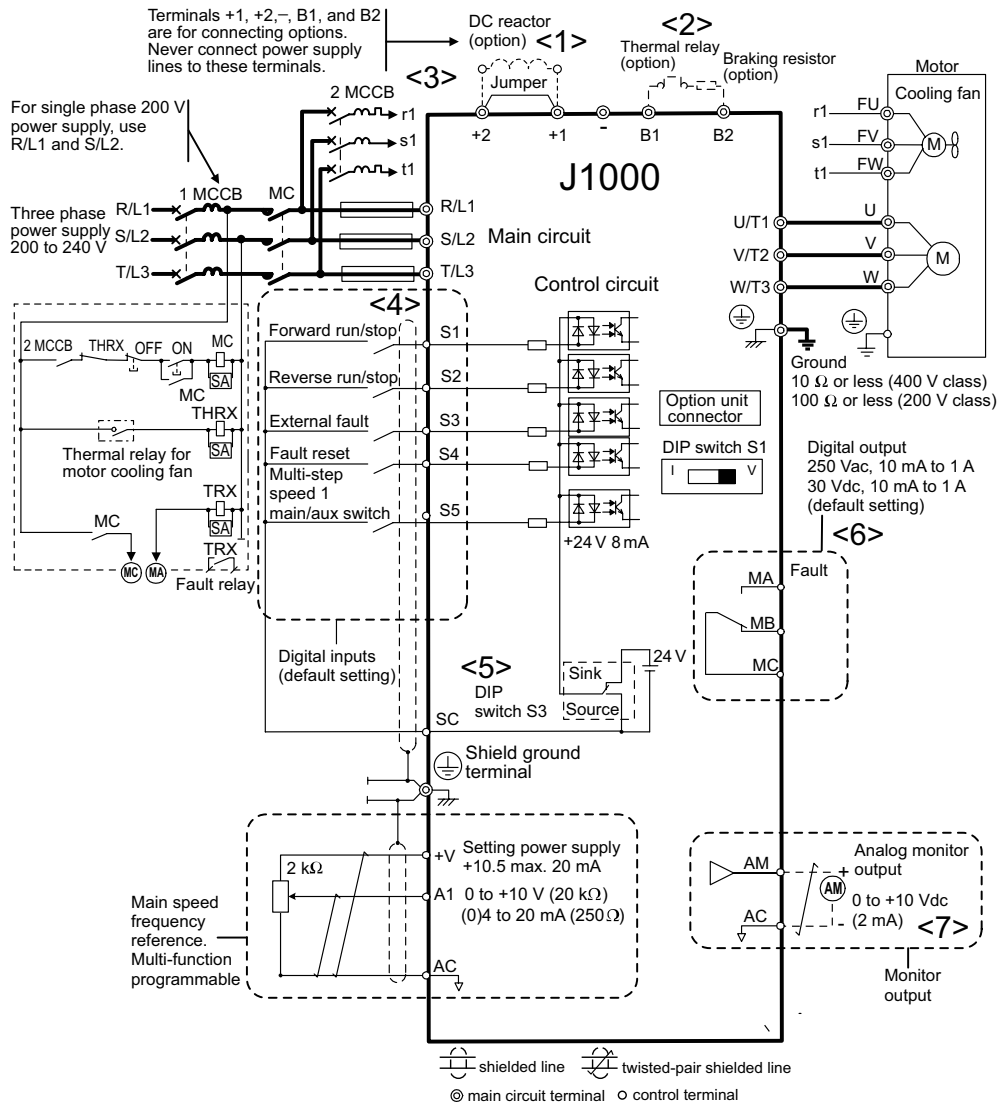


Inverter JZA □		DIN rail mounting bracket
3-phase 200 VAC	20P1/ 20P2 / 20P4/ 20P7	EZZ08122A
	21P5/ 22P2	EZZ08122B
	24P0	EZZ08122C
Single-phase 200 VAC	B0P1/ B0P2/ B0P4	EZZ08122A
	B0P7/ B1P5	EZZ08122B
3-phase 400 VAC	40P2/ 40P4/ 40P7/ 41P5/ 42P2	EZZ08122B
	44P0	EZZ08122C



# Installation

## Standard connections

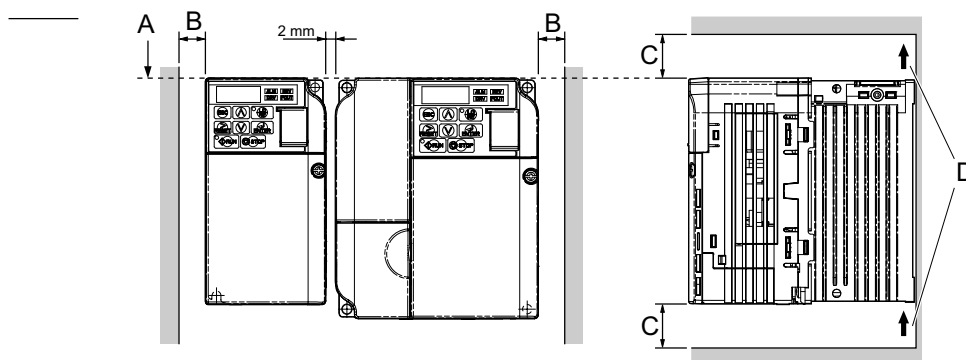


## Main circuit

Terminal	Name	Function (signal level)
R/L1, S/L2, T/L3	Main circuit power supply input	Used to connect line power to the drive. Drives with single-phase 200 V input power use only terminals R/L1 and S/L2 (T/L3 is not connected to anything)
U/T1, V/T2, W/T3	Inverter output	Used to connect the motor
B1, B2	Braking resistor connection	Available for connecting a braking resistor or the braking resistor unit option.
+2, +1	DC reactor connection	Remove the short bar between +2 and +1 when connecting DC reactor (option)
+1, -	DC power supply input	For power supply input (+1: positive electrode; - : negative electrode)*
⊕	Grounding	For grounding (grounding should conform to the local grounding code.)

## Control Circuit

Type	No.	Signal name	Function	Signal level
Digital input signals	S1	Multi-function input selection 1	Factory setting: runs when CLOSED, stops when OPEN.	24 VDC, 8 mA photocoupler insulation
	S2	Multi-function input selection 2	Factory setting: runs when CLOSED, stops when OPEN.	
	S3	Multi-function input selection 3	Factory setting: External Fault (N.O.)	
	S4	Multi-function input selection 4	Factory setting: Fault reset	
	S5	Multi-function input selection 5	Factory setting: Multi-step speed cmd 1	
	SC	Multi-function input selection Common	Common for control signal	
Analog input signal	FS	Power Supply for Frequency Setting	+10 V (allowable max current 20 mA)	
	FR1	Main Speed Freq Ref	Voltage input or current input 0 to +10 VDC (20 k $\Omega$ ) (resolution 1/1000) 4 to 20 mA (250 $\Omega$ ) or 0 to 20 mA (250 $\Omega$ ) Resolution: 1/500	
	FC	Frequency reference common	0 V	
Digital output signals	MA	NO contact output	Factory setting: "fault"	Contact capacity 250 VAC, 1 A or less 30 VDC, 1 A or less
	MB	NC Output		
	MC	Relay Output common		
Analog output signals	AM	Analog monitor output	Factory setting: "output frequency" 0 to +10 V output Resolution: 1/1000	0 to 10 V 2 mA or less Resolution: 8 bits
	AC	Analog monitor common	0 V	



A- Line up the tops of the drives.

B- 30 mm minimum.

C - 100 mm minimum

D - Airflow direction

## Inverter heat loss

### Three-phase 200 V class

Model JZA		20P1	20P2	20P4	20P7	21P5	22P2	24P0
Inverter capacity kVA		0.3	0.6	1.1	1.9	3.0	4.2	6.7
Rated current (A) at HD		0.8	1.6	3	5	8	11	17.5
Rated current (A) at ND		1.2	1.9	3.5	6.0	9.6	12.0	21.0
Heat loss W HD	Fin	4.3	7.9	16.1	27.4	54.8	70.7	110.5
	Inside unit	7.3	8.8	11.5	15.9	23.8	30.0	43.3
	Total heat loss	11.6	16.7	27.7	43.3	78.6	100.6	153.8
Heat loss W ND	Fin	4.7	7.2	14.0	35.6	48.6	57.9	93.3
	Inside unit	7.9	9.4	13.4	16.9	25.0	29.6	45.0
	Total heat loss	12.6	16.6	28.5	43.1	73.6	87.5	138.2
Cooling Method		Self Cooled			Fan Cooled			

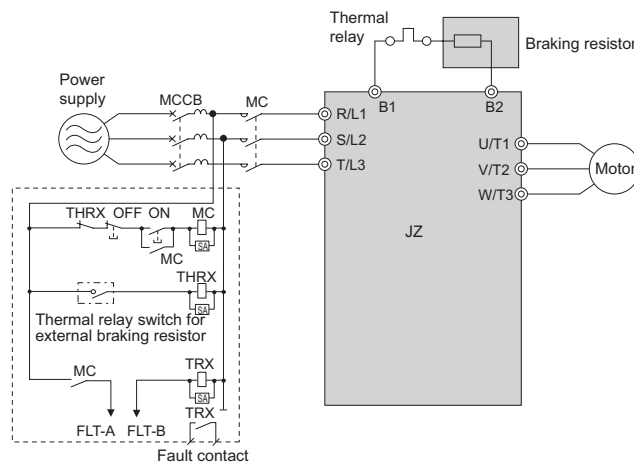
### Single-phase 200 V class

Model JZA		B0P1	B0P2	B0P4	B0P7	B1P5
Inverter capacity kVA		0.3	0.6	1.1	1.9	3.0
Rated current (A) at HD		0.8	1.6	3	5	8
Rated current (A) at ND		1.2	1.9	3.5	6.0	9.6
Heat loss W HD	Fin	4.3	7.9	16.1	42.5	54.8
	Inside unit	7.4	8.9	11.5	19.0	25.9
	Total heat loss	11.7	16.7	27.7	61.5	80.7
Heat loss W ND	Fin	4.7	7.2	15.1	26.2	48.6
	Inside unit	8.4	9.6	14.3	20.8	29.0
	Total heat loss	13.1	16.8	28.3	56.5	77.6
Cooling Method		Self Cooled			Fan Cooled	

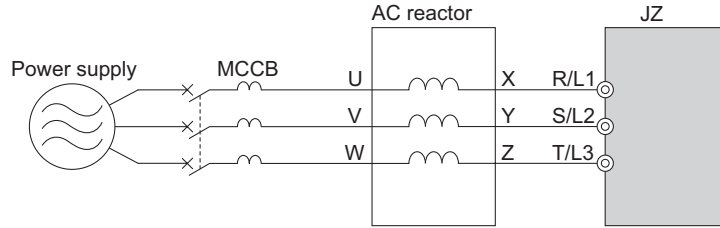
### Three-phase 400 V class

Model JZA		40P2	40P4	40P7	41P5	42P2	43P0	44P0
Inverter capacity kVA		0.9	1.4	2.6	3.7	4.2	5.5	7.2
Rated current (A) at HD		1.2	1.8	3.4	4.8	5.5	7.2	9.2
Rated current (A) at ND		1.2	2.1	4.1	5.4	6.9	8.8	11.1
Heat loss W HD	Fin	19.2	28.9	42.3	70.7	81.0	84.6	107.2
	Inside unit	11.4	14.9	17.9	26.2	30.7	32.9	41.5
	Total heat loss	30.6	43.7	60.2	96.9	111.7	117.5	148.7
Heat loss W ND	Fin	8.2	15.5	26.4	37.5	49.7	55.7	71.9
	Inside unit	9.2	13.1	15.8	20.0	26.3	29.4	43.6
	Total heat loss	17.4	28.6	42.2	57.5	76.0	85.1	115.5
Cooling Method		Self Cooled			Fan Cooled			

## Connections for braking resistor

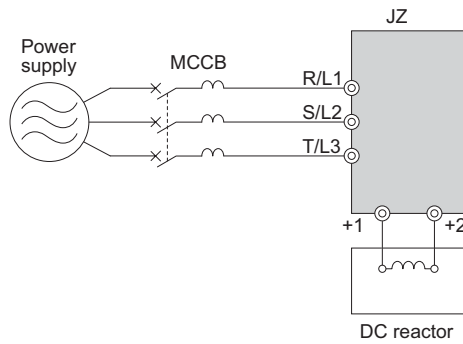


### AC reactor



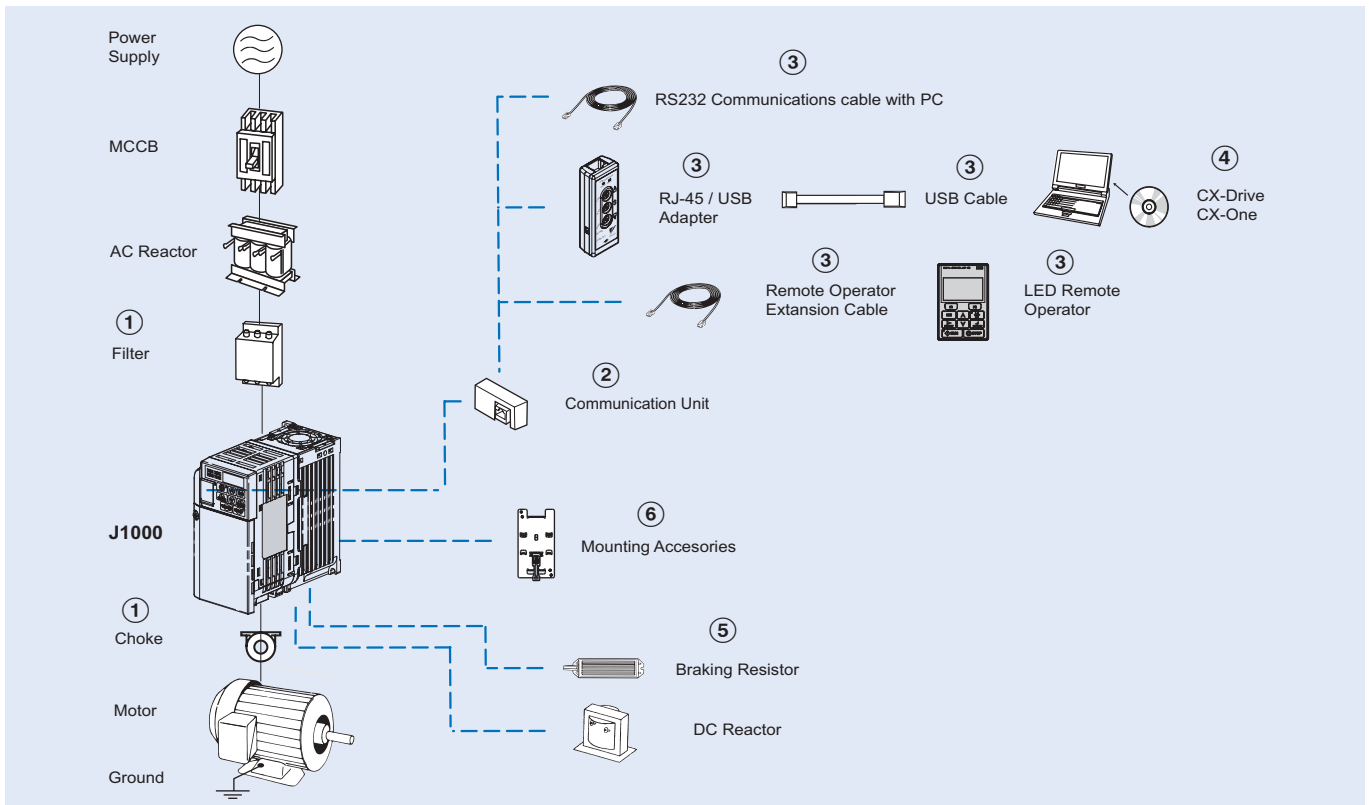
200 V class			400 V class		
Max. applicable motor output kW	Current value A	Inductance mH	Max. applicable motor output kW	Current value A	Inductance mH
0.12	2.0	2.0		-----	
0.25	2.0	2.0	0.2	1.3	18.0
0.55	2.5	4.2	0.4		
1.1	5	2.1	0.75	2.5	8.4
1.5	10	1.1	1.5	5	4.2
2.2	15	0.71	2.2	7.5	3.6
4.0	20	0.53	4.0	10	2.2

### DC reactor



200 V class			400 V class			
Max. applicable motor output kW	Current value A	Inductance mH	Max. applicable motor output kW	Current value A	Inductance mH	
0.12	5.4	8		-----		
0.25			0.2	3.2	28	
0.55						0.4
1.1						
1.5	18	3	1.5	5.7	11	
2.2			2.2			
4.0						4.0

## Ordering information



### J1000

	Specifications				Model
	Heavy Duty		Normal Duty		Standard
1x200 V	0.12 kW	0.8 A	0.18 kW	0.8 A	JZAB0P1BAA
	0.25 kW	1.6 A	0.37 kW	1.6 A	JZAB0P2BAA
	0.55 kW	3.0 A	0.75 kW	3.5 A	JZAB0P4BAA
	1.1 kW	5.0 A	1.1 kW	6.0 A	JZAB0P7BAA
	1.5 kW	8.0 A	2.2 kW	9.6 A	JZAB1P5BAA
3x200 V	0.12 kW	0.8 A	0.18 kW	0.8 A	JZA20P1BAA
	0.25 kW	1.6 A	0.37 kW	1.6 A	JZA20P2BAA
	0.55 kW	3.0 A	0.75 kW	3.5 A	JZA20P4BAA
	1.1 kW	5.0 A	1.1 kW	6.0 A	JZA20P7BAA
	1.5 kW	8.0 A	2.2 kW	9.6 A	JZA21P5BAA
	2.2 kW	11.0 A	3.0 kW	12.0 A	JZA22P2BAA
3x400 V	4.0 kW	17.5 A	5.5 kW	21.0 A	JZA24P0BAA
	0.37 kW	1.2 A	0.37 kW	1.2 A	JZA40P2BAA
	0.55 kW	1.8 A	0.75 kW	2.1 A	JZA40P4BAA
	1.1 kW	3.4 A	1.5 kW	4.1 A	JZA40P7BAA
	1.5 kW	4.8 A	2.2 kW	5.4 A	JZA41P5BAA
	2.2 kW	5.5 A	3.0 kW	6.9 A	JZA42P2BAA
	3.0 kW	7.2 A	4.0 kW	8.8 A	JZA43P0BAA
4.0 kW	9.2 A	5.5 kW	11.1 A	JZA44P0BAA	

### ① Line filters

Inverter		Line filter Schaffner			Line filter Rasmi		
Voltage	Model JZA□	Reference	Rated current (A)	Weight (kg)	Reference	Rated current (A)	Weight (kg)
3-Phase 200 VAC	20P1 / 20P2 / 20P4 / 20P7	A1000-FIV2010-SE	10	0.7	A1000-FIV2010-RE	10	0.8
	21P5 / 22P2	A1000-FIV2020-SE	20	0.9	A1000-FIV2020-RE	20	1.1
	24P0	A1000-FIV2030-SE	30	1.0	A1000-FIV2030-RE	30	1.3
Single-Phase 200 VAC	B0P1 / B0P2 / B0P4	A1000-FIV1010-SE	10	0.5	A1000-FIV1010-RE	10	0.6
	B0P7 / B1P5	A1000-FIV1020-SE	20	0.7	A1000-FIV1020-RE	20	1.0
3-Phase 400 VAC	40P2 / 40P4	A1000-FIV3005-SE	5	0.5	A1000-FIV3005-RE	5	1.1
	40P7 / 41P5 / 42P2 / 43P0	A1000-FIV3010-SE	10	0.75	A1000-FIV3010-RE	10	1.1
	44P0	A1000-FIV3020-SE	15	1.0	A1000-FIV3020-RE	20	1.3

### Chokes

Model	Diameter	Description
A1000-FEV2102-RE	21	Recommended for motors below 2.2 KW
A1000-FEV2515-RE	25	Recommended for motors below 15 KW

### ② Communication cards

Type	Model	Description	Function
Option units	SI-232/JC	RS-232C serial communication interface	• RS232C communications interface to connect the drive to a PC or the optional copy unit
	SI-232/J	Remote operator interface	• RS232C communication interface for usage with the external LED operator JVOP-182
	SI-485/J	RS-422/485 Serial communications interface	• Interface for RS-422/485 communications using the MEMOBUS/Modbus RTU protocol
	AI-V3/J	Potentiometer Option	• Potentiometer option for setting the frequency reference directly at the drive

### ③ Accessories

Types	Model	Description	Functions
Digital operator	JVOP-182	LED remote operator	Remote operator with LED display and copy function, cable length max. 3m.
	A1000-CAVOP300-EE	Remote operator cable	3 meters cable for connecting remote operator
Accessories	JVOP-181	USB converter / USB cable	Allows the user to copy and verify parameter settings between drives. Can also be used as adapter to connect the drive to a PC USB port. SI-232/JC option is required
	A1000-CAVPC232-EE	PC connection cable	RS232 PC tool connection cable

### ④ Computer software

Types	Model	Description	Installation
Software	CX-drive	Computer software	Configuration and monitoring software tool
	CX-One	Computer software	Configuration and monitoring software tool

⑤ Braking unit, braking resistor unit

Voltage	Inverter				Braking resistor unit			
	Max. applicable motor output kW	Inverter model JZA□		Connectable min. resistance Ω	Inverter-mounted type (3 %ED, 10 sec max)			
		3-phase	1-phase		Type	Resistance Ω	No. of used	Braking torque %
200 V (single-/ three-phase)	0.12	20P1	B0P1	300	A1000-REJ0K15400-IE	400	1	220
	0.25	20P2	B0P2	300				220
	0.55	20P4	B0P4	200	A1000-REJ0K15200-IE	200	1	220
	1.1	20P7	B0P7	120				125
	1.5	21P5	B1P5	60	A1000-REJ0K15100-IE	100	1	125
	2.2	22P2	-	60	A1000-REJ0K15070-IE	70	1	120
	4.0	24P0	-	32	A1000-REJ0K15062-IE	62	1	100
400 V (three-phase)	0.37	40P2	-	750	A1000-REJ0K10750-IE	750	1	230
	0.55	40P4	-	750				230
	1.1	40P7	-	510				130
	1.5	41P5	-	240	A1000-REJ0K15400-IE	400	1	125
	2.2	42P2	-	200	A1000-REJ0K15300-IE	300	1	115
	3.0	43P0	-	100	A1000-REJ0K15400-IE	400	2	105
	4.0	44P0	-					

⑥ Mounting accessories

Types	Model	Description	Applicable models JZA□
DIN Rail	EZZ08122A	Necessary to mount the inverter on a DIN rail	20P1/20P2/20P4/20P7 B0P1/B0P2/B0P4
	EZZ08122B		21P5/22P2 B0P7/B1P5 40P2/40P4/40P7/41P5/42P2
	EZZ08122C		24P0 B2P2 44P0
Heatsink external mounting attachment	100-034-075	Additional items to mount the inverter with the heat-sink out of the panel.	20P1/20P2 B0P1/B0P2
	100-034-076		20P4 B0P4
	100-034-077		20P7
	100-034-078		40P2
	100-034-79		21P5/22P2 B1P5 41P5/42P2/43P0
	100-034-80		24P0 B2P2 44P0
	100-036-357		B4P0
	100-036-418		B0P7 40P4/40P7

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.